

## GPS & BDS Antenna Module



### 1. Product Information

#### 1.1 Product Name: YIC82525GMGB

#### 1.2 Product Description:

YIC82525GMGB is a compact, high performance, and low power consumption GNSS engine board. It uses the chipset which can track up to 32 channels at a time and perform fast TTFF in weak signal environments.

YIC82525GMGB is suitable for the following applications:

- Automotive navigation
- Personal positioning
- Fleet management
- Mobile phone navigation
- Marine navigation

#### 1.3 Product Features:

- High performance and low power consumption GPS Chipset
- Very high sensitivity
- Extremely fast TTFF (Time To First Fix) at low signal level
- Two serial ports
- Built-in LNA
- Compact size suitable for space-sensitive application
- One size component, easy to mount on another PCB board
- Support NMEA 0183 and Realtek binary protocol

## 1.4 Product Specifications

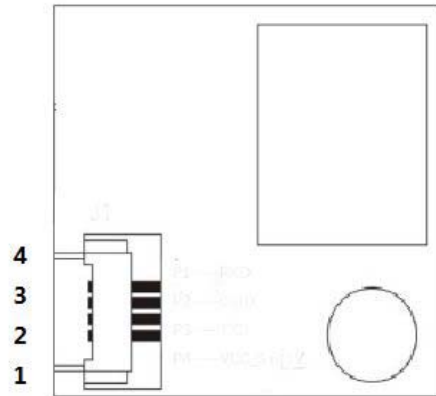
### GPS Performance

GNSS Receiver	
Chip	REALTEK RTL8771AW
Frequency	GPS, QZSS: L1 1575.42MHz, C/A code, BD: 1561.098MHz
Code	C/A Code
Available Baud Rate	9,600 bps
Channels	Support 32
Sensitivity	Tracking:-161dBm Reacquisition:-160dBm ColdStart:-148dBm
Cold Start	31 seconds, average
Warm Start	28 seconds, average
Hot Start	8 seconds, average
Accuracy	3m (2D RMS).
Maximum Altitude	50,000 meter
Maximum Velocity	280 m/s(1000 knots)
Dynamics	≦4G
Update Rate	4 Hz
A-GPS	AssistNow on-line and off-line
Interface	
I/O Pins	1 serial ports
Physical Characteristic	
Dimensions	25.1mm * 25.1 mm * 8.8mm
DC Characteristics	
Power Supply	3.3~5.5VDC ± 5%

GPS Mode Power Consumption		
Power Consumption	Max Performance: Acquisition:75mA Tracking: 55mA	
GPS/BeidouMode Power Consumption		
Power Consumption	Max Performance: Acquisition:80mA Tracking: 65mA	
GPS/GlonassMode Power Consumption		
Power Consumption	Max Performance: Acquisition:76mA Tracking: 60mA	
Environmental Range		
Humidity Range	5% to 95% non-condensing	
Operation Temperature	-30°C to 75°C	
Storage Temperature	-40°C to 85°C	
Protocol Support	NMEA 0183	9600 bps, 8 data bits, no parity, 1 stop bits (default) 1Hz: GGA, GLL, GSA, GSV, RMC, VTG,ZDA

## 2. Technical Information

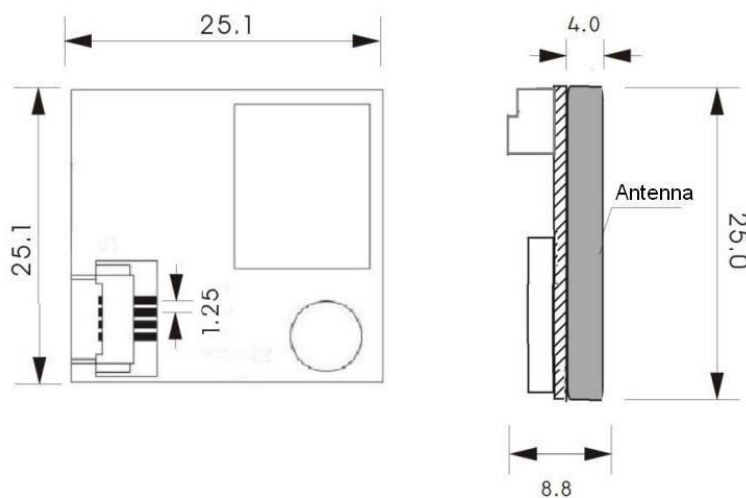
### Module Pin Assignment



尺寸单位: mm

Pin NO.	Pin Name	I/O	Remark
1.	VCC		+3.3~5.5V
2.	TXD	O	
3.	GND	G	Ground.
4.	RXD	I	

### Dimensions



Unit : mm

## 3. Application guideline

### Layout Rules

Do not routing the other signal or power trace under the engine board .

### Design Notes

#### GND

Ground pin for the baseband circuit.

#### RXD

This is the main channel for receiving software commands.

#### TXD

This is the main transmits channel for outputting navigation and measurement data to user's navigation software or user written software.

## 4. NEMA 0183 Protocol

The NMEA protocol is an ASCII-based protocol, Records start with a \$ and with carriage return/line feed. GPS specific messages all start with \$GPxxx where xxx is a three-letter identifier of the message data that follows. NMEA messages have a checksum, which allows detection of corrupted data transfers.

YIC82525GMGB modules support the following NMEA-0183 messages: GGA,VTG,RMC,GLL,GSA, GSV and ZDA.

Table 1: NMEA-0183 Output Messages

Item	Name	Data	Length(approximation), unit bytes(note 1)
0	GGA	UTC, latitude/longitude, position fixed, number of satellites in positioning, HDOP, height, DGPS	71
1	VTG	Forward direction, magnetic trace degree, speed	37
2	RMC	UTC, data status, latitude/longitude, speed, forward direction, UTC days, magnetic trace degree, position mode	61
3	GLL	latitude/longitude, UTC time, status	44
4	GSA	Position mode, position calculation mode, PRN, PDOP, HDOP, VDOP	66
5	GSV	Total of GSV message , Serial number of GSV message, Number of visible satellites, PRN No. of 1st satellite, Elevation angle of 1st satellite (00~90 degree), Direction angle of 1st satellite (000~359 degree), SNR signal strength C/No of 1st satellite (00~99 dB)	70
6	ZDA(note 2)	Date and time	36
<p><b>Note 1</b> : The actual length will be due to the time, latitude and longitude of the display of the number of decimal places, satellite number definition, statement format and a slight adjustment.</p> <p><b>Note 2</b> : This statement should be generated by the original factory customized.</p>			

## 4.1 GGA

Excerpts from the NMEA0183 agreement are as follows:

```
$GPGGA, hhhmss, xxxx.xxx, a, yyyyy.yyy, a, x, x, xx, uxxxx, M, uxxx, M, xx, xxxx *hh<CR><LF>
      1 23 45 67 8   9 10 11 12 13 14
```

- 1: UTC (Hour, Minute, Second)
- 2,3: Latitude (Degree, Minute, N/S (the datum specified by user)
- 4,5: Longitude (Degree, Minute), E/W (the datum specified by user)
- 6: GPS position fixed information
  - 0: No positioning or invalid data,
  - 1: GPS positioning,
  - 2: Differential GPS positioning
- 7: Number of satellites for positioning
- 8: HDOP
- 9,10: Antenna height above mean sea level (m) (the datum specified by user)
- 11,12: Geoidal height (m)
- 13: DGPS data correction lapsed time (second), 00 when non DGPS positioning.
- 14: DGPS Reference Station No., 0000 when non DGPS positioning.

Example:

```
$GPGGA,044103.00,2446.78905,N,12059.72063,E,1,12,0.8,160.8,M,19.5,M,,*6F
```

Table 4.1: GGA Table

Name	Example	Units	Description
Message ID	\$\$sGGA		GGA protocol header, %s please reference to Table 2.1
UTC Time	044103.00		hhmmss.ss
Latitude	2446.78905		ddmm.mmmmm
N/S indicator	N		N=north or S=south
Longitude	12059.7206 3		dddmm.mmmmm
E/W indicator	E		E=east or W=west
Position Fix Indicator	1		See table
Satellites Used	12		Range 00 to 12
HDOP	0.8		Horizontal Dilution of Precision
MSL Altitude	160.8	meters	Altitude above mean sea level
Units	M	meters	
Geoids Separation	19.5	meters	Separation from Geoids, can be blank
Units	M	meters	
Age of Diff. Corr.		second	Null fields when DGPS is not used
Diff. Ref.Station ID			Null fields when DGPS is not used
Checksum	*6F		
<CR><LF>			End of message terminal(ASCII 13 ASCII 10)

## 4.2 VTG

Excerpts from the NMEA0183 agreement are as follows:

```
$GPVTG,xxx.x,T,,M,xxx.x,N,xxx.x,K,A*hh<CR><LF>
  123 4 5 6 7 8 9
```

1,2: Track Degrees (degree), T = True

3,4: Track Degrees(degree), M = Magnetic

5,6: Speed (knot)

7,8: Speed (km/h)

9: Mode indication (NMEA0183 only version 3.01 A= output, self localization, D= difference, E= estimates, N= data is invalid)

Example:

```
$GPVTG,000.00,T,,M,000.02,N,000.03,K,A*51
```

Table 4.2: VTG Table

Name	Example	Units	Description
Message ID	\$%sVTG		VTG protocol header, %s please reference to Table 2.1
Track Degrees	000.00	degree	ddd.dd
	T		
Track Degrees		drgree	Null if no E-compass or magnetic sensor
	M		
Speed	000.02		ddd.dd, speed represents in knot
	N	Knots	
Speed			ddd.dd, speed represents in km/hr
	K	Km/hr	
mode	A		Mode indication (NMEA0183 only version3.01 A= output, self localization, D= difference, E= estimates, N= data is invalid)
Checksum	*51		
<CR><LF>			End of message terminal(ASCII 13 ASCII 10)



## 4.3 RMC

Excerpts from the NMEA0183 agreement are as follows:

```
$GPRMC,hhmmss.ss,f,ddmm,mm,a,dddmm.mm,a,xxx.x,xxx.,xxxxxx, x.x, b, c*hh<CR><LF>
  1 2 3 4 5 6 7 8 9 10 11 12
```

1: UTC (Hour, Minute, Second)

2: Data status A: Valid, V: Invalid

3,4: Latitude (degree, minute), N/S (the datum specified by user)

5,6: Longitude(degree, minute), E/W (the datum specified by user)

7: Speed (knots)

8: Forward Direction (degree)

9: UTC day, month, year

10: Declination(000.0~180.0 degrees, in front of 0 will also be transmitted)

11: Declination direction , E ( east ) or W ( west )

12: Mode indication (NMEA0183 only version3.01 A= output, self localization, D= difference, E= estimates, N= data is invalid)

Example:

```
$GPRMC,044103.00,A,2446.78905,N,12059.72063,E,000.02,000.00,160715,,,A*52
```

Table 4.3: RMC Table

Name	Example	Units	Description
Message ID	\$%sRMC		RMC protocol header, %s please reference to Table 2.1
UTC Time	044103.00		hhmmss.ss
Data status	A		A: valid, V: invalid
Latitude	2446.78905		ddmm.mmmmm
N/S indicator	N		N=north or S=south
Longitude	12059.7206 3		Dddmm.mmmmm
E/W indicator	E		E=east or W=west
Speed	000.02	knots	Speed in knots
Forward direction	000.00	degree	ddd.dd
UTC day	160715		ddmmyy
Declination(magnetic variation)		degree	Null if no e-compass or magnetic sensor exists

Declination direction(E/W indicator)			E=east or W=west, null if no e-compass or magnetic sensor exists
mode	A		Mode indication (NMEA0183 only version3.01 A= output, self localization, D= difference, E= estimates, N= data is invalid)
Checksum	*52		
<CR><LF>			End of message terminal(ASCII 13 ASCII 10)

#### 4.4 GLL

Excerpts from the NMEA0183 agreement are as follows:

`$GPGLL,ddmm.mm, a, dddmm.mm, a, hhhmmss.ss, A ,B*hh<CR><LF>`

1 2 3 4 5 6 7

1,2: Latitude (degree, minute), N/S

3,4: Longitude(degree, minute), E/W

5: UTC (hour, minute, second)

6: Status A=Valid V=Invalid

7: Mode indication (NMEA0183 only version3.01 A= output, self localization, D= difference, E= estimates, N= data is invalid))

Example:

`$GPGSA,A,3,01,04,23,07,09,11,193,27,16,19,22,28,1.1,0.8,0.8*03`

Table 4.4: GLL Table

Name	Example	Units	Description
Message ID	<code>1234567890</code>		GLL protocol header, %s please reference to Table 2.1
Latitude	2446.78905		ddmm.mmmmm
N/S indicator	N		N=north or S=south
Longitude	12059.7206 3		Dddmm.mmmmm
E/W indicator	E		E=east or W=west
UTC Time	044103.00		hhmmss.ss
Data status	A		A: valid, V: invalid
mode	A		Mode indication (NMEA0183 only version3.01 A= output, self localization, D= difference, E= estimates, N= data is invalid)
Checksum	*52		
<CR><LF>			End of message terminal(ASCII 13 ASCII 10)

## 4.5 GSA

Excerpts from the NMEA0183 agreement are as follows:

```
$GPGSA,a,x,xx,xx,xx,xx,xx,xx,xx,xx,xx,xx,xx,x,xx,x,
  1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16
  xx.x*hh<CR><LF>
  17
```

1: Positioning mode M = Manual (2 or 3 dimension). A = AUTO

2: Positioning Calculation Mode

1 = not positioning, 2 = 2 dimension, 3 = 3 dimension

3~14: Satellite PRN No. ("00" for no satellite in case of less than 12 satellites)

15: PDOP

16: HDOP

17: VDOP

Example:

```
$GPGSA,A,3,01,04,23,07,09,11,19,3,27,16,19,22,28,1.1,0.8,0.8*03
```

Table 4.5: GSA Table

Name	Example	Units	Description
Message ID	\$%sGSA		GSA protocol header, %s please reference to Table 2.1
Positioning mode	A		M = Manual (2 or 3 dimension). A = AUTO
Positioning calculation mode	3		1 = not positioning, 2 = 2 dimension, 3 = 3 dimension
Satellite PRN number	01,04,23,07,09,11,19,3,27,16,19,22,28		"00" for no satellite in case of less than 12 satellites
PDOP	1.1		
HDOP	0.8		
VDOP	0.8		
Checksum	*03		
<CR><LF>			End of message terminal(ASCII 13 ASCII 10)

## 4.6 GSV

Excerpts from the NMEA0183 agreement are as follows:

```
$GPGSV,x,x,xx,xx,xx,xxx,xx,xx,xx,xxx,xx,xx,xx,xxx,xx,xx,
  1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16
  xx,xxx,xx*hh<CR><LF>
1718 19
```

- 1: Total of GSV message
- 2: Serial number of GSV message
- 3: Number of visible satellites
- 4: PRN No. of 1st satellite
- 5: Elevation angle of 1st satellite (00~90 degree)
- 6: Direction angle of 1st satellite (000~359 degree)
- 7: SNR signal strength C/No of 1st satellite (00~99 dB)
- 8~11: Data of 2nd satellite (same order as 4~7)
- 12~15: Data of 3rd satellite (same order as 4~7)
- 16~19: Data of 4th satellite (same order as 4~7) \* "00" and "000" for no satellite in case of less than 4 satellites. In case of more than 5 satellites, 2 sentences are employed and in case of more than 9 satellites, 3 sentences are employed.

Example:

```
$GPGSV,4,1,14,01,49,181,49,04,68,136,51,07,57,304,49,09,16,232,42*7E
$GPGSV,4,2,14,11,70,208,49,16,22,089,43,19,51,016,50,22,01,068,35*7C
$GPGSV,4,3,14,23,09,197,43,27,25,041,45,28,03,300,42,193,35,138,45*47
$GPGSV,4,4,14,03,00,000,26,30,00,000,47*7B
```

Table 4.6: GSV Table

Name	Example	Units	Description
Message ID	14,01,49,181,49,04,68,136,51,07,57,304,49,09,16,232,42		GSV protocol header, %s please reference to Table 2.1
Total of GSV messages	4		Total GSV message number, here is 4 lines
Serial number of GSV message	1~4		The serial number of current GSV message
Number of visible satellites	14		Number of all visible satellites
PRN	01,04,07,09 in		Prn of all visible satellites

	line1 11,16,19,22 in line 2 23,27,28,193 in line 3 03,30 in line 4		
Elevation angle	49,68,57,16 in line 1 70,22,51,01 in line 2 09,25,03,35 in line 3 00,00 in line 4	degre e	Elevation angle of all visible satellites
Azimuth angle	181,136,304,232 in line 1 208,089,016,068 in line 2 197,041,300,138 in line 3 000,000 in line 4	Degre e	Azimuth angle of all visible satellites
SNR	49,51,49,42 in line 1 49,43,50,35 in line 2 43,45,42,45 in line 3 26,47 in line 4	dB	SNR signal strength C/No
Checksum	*7E in line 1 *7C in line 2 *47 in line 3 *7B in line 4		
<CR><LF>			End of message terminal(ASCII 13 ASCII 10)

## 4.7 ZDA

Excerpts from the NMEA0183 agreement are as follows:

`$GPZDA,hhmmss.ss,xx,xx,xxxx,xx,xx*hh`

1 2 3 4 5 6

- 1: Time (UTC)
- 2: Day, 01 to 31
- 3: Month, 01 to 12
- 4: Year
- 5: Local zone hour description, 00 to +/- 13 hours
- 6: Local zone minutes description, same sign as local hours, 00~59

Example:

`$GPZDA,201530.00,04,07,2002,00,00*60`

Table 4.7: ZDA Table

Name	Example	Units	Description
Message ID	<code>\$\$sZDA</code>		GSV protocol header, %s please reference to Table 2.1
Time ( UTC)	201530.00		hhmmss.ss
Day	04		dd
Month	07		mm
Year	2002		yyyy
Local zone hour description	00		hh
Local zone minute description	00		mm
Checksum	*60		
<CR><LF>			End of message terminal(ASCII 13 ASCII 10)

## 5. Example

### 5.1 Format

1. Support GGA/GLL/GSA/GSV/RMC/VTG;
2. Single and double mode at the beginning of the unified format for GP,GSA/GSV different mode satellite merger display;
3. BD prn 141~178, GLONASS prn 53~76;
4. Single mode statement sequence: GPGGA -> GPGLL -> GPGSA -> GPGSV -> GPRMC -> GPVTG
5. Two mode statement sequence: GPGGA -> GPGLL -> GPGSA -> GPGSV -> GPRMC -> GPVTG

### 5.2 GPS Single mode positioning

GPS:02,05,06,07,12,13,15,20,29,30,50,193

NMEA Capture examples:

\$GPGGA,103124.00,2446.78971,N,12059.71961,E,1,12,0.89,168.6,M,19.5,M,,\*5C

\$GPGLL,2446.78971,N,12059.71961,E,103124.00,A,A\*6F

\$GPGSA,A,3,02,193,05,06,07,30,20,15,29,13,12,50,1.25,0.89,0.86\*3C

\$GPGSV,3,1,12,02,65,079,50,05,53,359,51,06,31,111,47,07,08,054,40\*76

\$GPGSV,3,2,12,12,03,225,39,13,71,186,51,15,37,219,49,20,30,289,48\*72

\$GPGSV,3,3,12,29,29,308,48,30,19,083,43,50,50,133,50,193,65,044,49\*4B

\$GPRMC,103124.00,A,2446.78971,N,12059.71961,E,0.042,0.000,040915,,A\*57

\$GPVTG,0.000,T,,M,0.042,N,0.079,K,A\*05

### 5.3 GPS/BeidouDual mode positioning

GPS:04,08,09,16,19,22,23,27,28,30,32,193,50,26

Beidou:146,147,148,150,151,152,141,173

NMEA Capture examples:

\$GPGGA,013008.00,2446.79039,N,12059.71897,E,1,17,0.68,160.8,M,19.5,M,,\*53

\$GPGLL,2446.79039,N,12059.71897,E,013008.00,A,A\*6C

\$GPGSA,A,3,09,28,32,19,08,04,27,193,23,16,22,147,0.98,0.68,0.71\*07

\$GPGSV,6,1,22,04,72,117,50,08,51,012,49,09,13,228,39,16,18,096,42\*71

\$GPGSV,6,2,22,19,57,358,49,22,02,062,37,23,05,191,40,27,21,045,43\*7F

\$GPGSV,6,3,22,28,06,304,42,30,60,294,00,32,09,137,42,193,37,139,45\*45

\$GPGSV,6,4,22,50,00,000,47,26,00,000,28,146,04,174,37,147,72,162,49\*7D

\$GPGSV,6,5,22,148,67,309,49,150,76,295,49,151,03,242,37,152,48,271,49\*72  
\$GPGSV,6,6,22,141,00,000,52,173,00,000,51\*7B  
\$GPRMC,013008.00,A,2446.79039,N,12059.71897,E,0.020,0.000,040915,,A\*50  
\$GPVTG,0.000,T,,M,0.020,N,0.036,K,A\*0A

#### 5.4 GPS/GLONASS Dual mode positioning

GPS:01,03,04,07,08,11,17,19,27,28,30,32,193  
GLONASS:62,74,61,57,72,71,73,56

#### NMEA Capture examples

\$GPGGA,025616.00,2446.79076,N,12059.72056,E,1,19,0.85,163.8,M,19.5,M,,\*5C  
\$GPGLL,2446.79076,N,12059.72056,E,025616.00,A,A\*6D  
\$GPGSA,A,3,01,193,03,04,07,08,11,19,28,32,30,17,1.21,0.85,0.86\*37  
\$GPGSV,6,1,21,01,76,030,51,03,29,144,45,04,46,038,49,07,47,215,48\*7C  
\$GPGSV,6,2,21,08,29,052,45,11,60,021,50,17,16,279,40,19,33,042,47\*7F  
\$GPGSV,6,3,21,27,00,073,00,28,32,326,47,30,50,269,49,32,27,099,45\*72  
\$GPGSV,6,4,21,193,52,129,48,62,72,282,51,74,00,248,00,61,41,172,39\*4E  
\$GPGSV,6,5,21,57,14,104,35,72,43,355,44,71,09,041,43,73,36,285,49\*72  
\$GPGSV,6,6,21,56,07,055,40\*4A  
\$GPRMC,025616.00,A,2446.79076,N,12059.72056,E,0.022,0.000,040915,,A\*53  
\$GPVTG,0.000,T,,M,0.022,N,0.040,K,A\*09